Autonics

• Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.

- A symbol indicates caution due to special circumstances in which hazards may occur.
- Marning Failure to follow instructions may result in serious injury or death

Safety Considerations

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
- Failure to follow this instruction may result in explosion or fire. **03. Install on a device panel to use.** Failure to follow this instruction may result in electric shock.
- Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire or electric shock. **05. Check 'Connections' before wiring.**
 - Failure to follow this instruction may result in fire.

06. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire or electric shock.

- ▲ Caution Failure to follow instructions may result in injury or product damage
- 01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N · m.

When connecting the sensor input and communication cable without dedicated cable, use AWG 27 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m..

Failure to follow this instruction may result in fire or malfunction due to contact failure.

- 02. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage 03. Use a dry cloth to clean the unit, and do not use water or organic solvent.
- Failure to follow this instruction may result in fire or electric shock.04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length.
 For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case
 installing power line and input signal line closely, use line filter or varistor at power line
 and shielded wire at input signal line. Do not use near the equipment which generates
 strong magnetic force or high frequency noise.

Bar Graph Temperature Controllers



KPN Series PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

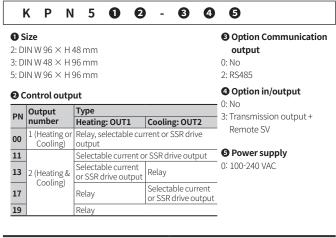
Features

- High speed sampling of 50ms and $\pm 0.3\%$ display accuracy
- Enable to check control output operation amount by adopting bar graph
- Simultaneous heating/cooling control and automatic/manual control for high performance control
- Selection function of current output or SSR drive output
- Parameter setting available via PC (USB and RS485 communication)
 Free device comprehensive management program (DAQMaster)
- Communication converter sold separately: SCM-US (USB/Serial converter), SCM-38I (RS232C/RS485 converter) SCM-US48I (USB/RS485 converter)
- Multi-SV (Max. 4) function (select via digital input terminal)
- Heater break alarm
- CT sold separately: CSTC-E80LN, CSTC-E200LN, CSTS-E80PP
- Small size (rear length: 60 mm)
- Multi input/multi range

- Do not apply excessive power when connecting or disconnecting the connectors of the product.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- Power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise.
- Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications') - Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website .



Product Components

• Product (+ bracket)

Instruction manual

Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.

Download the manuals from the Autonics website.

Software

Download the installation file and the manuals from the Autonics website.

DAQMaster

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

Sold Separately

- Terminal protection cover: RHA / RLA-COVER
 • Current transformer (CT)
- Communication Converter: SCM-US / SCM-38I / SCM-US48I / SCM-WF48

ply e voltage sumption period ification CT input teavote SV bigital input telay SR SR current telay arrent	KPN Series 100 - 240 VAC \sim 50/60 Hz 90 to 110 % of rated voltage \leq 15 VA 50 ms Refer to 'Input Type and Using Range'. • 0.0-50.0 A (primary current measurement range) • CT ratio: 1/1,000 1 - 5 VDC= or 4 - 20 mA (Current Input: External resistance 250 Ω) • Contact - ON: \leq 2 kΩ, OFF: \geq 90 kΩ • Non contact - residual voltage \leq 1.0 V, leakage current \leq 0.1 mA 250 VAC \sim 5 A 1a 11 VDC==±2 V, \leq 20 mA			
e voltage sumption period ification .T input teemote SV objgital input telay .SR current telay	90 to 110 % of rated voltage $\leq 15 \text{ VA}$ 50 ms Refer to 'Input Type and Using Range'. • 0.0-50.0 A (primary current measurement range) • CT ratio: 1/1,000 1 - 5 VDC= or 4 - 20 mA (Current Input: External resistance 250 Ω) • Contact - ON: $\leq 2 \text{ k}\Omega$, OFF: $\geq 90 \text{ k}\Omega$ • Non contact - residual voltage $\leq 1.0 \text{ V}$, leakage current $\leq 0.1 \text{ mA}$ 250 VAC~ 5 A 1a 11 VDC== $\pm 2 \text{ V}$, $\leq 20 \text{ mA}$			
e voltage sumption period ification .T input teemote SV objgital input telay .SR current telay	90 to 110 % of rated voltage $\leq 15 \text{ VA}$ 50 ms Refer to 'Input Type and Using Range'. • 0.0-50.0 A (primary current measurement range) • CT ratio: 1/1,000 1 - 5 VDC= or 4 - 20 mA (Current Input: External resistance 250 Ω) • Contact - ON: $\leq 2 \text{ k}\Omega$, OFF: $\geq 90 \text{ k}\Omega$ • Non contact - residual voltage $\leq 1.0 \text{ V}$, leakage current $\leq 0.1 \text{ mA}$ 250 VAC~ 5 A 1a 11 VDC== $\pm 2 \text{ V}$, $\leq 20 \text{ mA}$			
period ification T input temote SV bigital input telay SR SR turrent telay	50 ms Refer to 'Input Type and Using Range'. • 0.0-50.0 A (primary current measurement range) • CT ratio: 1/1,000 1 - 5 VDC= or 4 - 20 mA (Current Input: External resistance 250 Ω) • Contact - ON: $\leq 2 k\Omega$, OFF: $\geq 90 k\Omega$ • Non contact - residual voltage $\leq 1.0 V$, leakage current $\leq 0.1 mA$ 250 VAC~ 5 A 1a 11 VDC= $\pm 2 V$, $\leq 20 mA$			
ification CT input Remote SV Digital input Relay SR Rurrent Relay	Refer to 'Input Type and Using Range'. • 0.0-50.0 A (primary current measurement range) • CT ratio: 1/1,000 1 - 5 VDC= or 4 - 20 mA (Current Input: External resistance 250 Ω) • Contact - ON: $\leq 2 k\Omega$, OFF: $\geq 90 k\Omega$ • Non contact - residual voltage $\leq 1.0 V$, leakage current $\leq 0.1 mA$ 250 VAC~ 5 A 1a 11 VDC= $\pm 2 V$, $\leq 20 mA$			
T input temote SV bigital input telay SR current telay	• 0.0-50.0 A (primary current measurement range) • CT ratio: 1/1,000 1 - 5 VDC= or 4 - 20 mA (Current Input: External resistance 250 Ω) • Contact - ON: $\leq 2 k\Omega$, OFF: $\geq 90 k\Omega$ • Non contact - residual voltage $\leq 1.0 V$, leakage current $\leq 0.1 mA$ 250 VAC $\sim 5 A 1a$ 11 VDC= $\pm 2 V$, $\leq 20 mA$			
igital input kelay SR Current telay	$\begin{array}{l} 1-5VDC = or4-20mA(Current Input: External resistance250\Omega)\\ \bulletContact-ON:\leq 2k\Omega,OFF:\geq 90k\Omega\\ \bulletNoncontact-residualvoltage\leq 1.0V, leakagecurrent\leq 0.1mA\\ 250VAC\sim 5A1a\\ 11VDC = \pm 2V,\leq 20mA \end{array}$			
Digital input Relay SR Current Relay	• Contact - ON: $\leq 2 \text{ k}\Omega$, OFF: $\geq 90 \text{ k}\Omega$ • Non contact - residual voltage $\leq 1.0 \text{ V}$, leakage current $\leq 0.1 \text{ mA}$ 250 VAC~ 5 A 1a 11 VDC== $\pm 2 \text{ V}$, $\leq 20 \text{ mA}$			
eelay SR Current Relay	• Non contact - residual voltage \leq 1.0 V, leakage current \leq 0.1 mA 250 VAC~ 5 A 1a 11 VDC== \pm 2 V, \leq 20 mA			
SR Current Celay	$11 \text{ VDC} = \pm 2 \text{ V}, \le 20 \text{ mA}$			
Current Relay				
elay				
	DC 4-20 mA or DC 0-20 mA (parameter), load resistance: \leq 500 Ω			
ranemission	250 VAC~ 3 A 1a			
	DC 4 - 20 mA (load resistance: \leq 500 Ω , output accuracy: \pm 0.3% F.S. \pm 1-digit)			
S485 Comm.	Modbus RTU			
be	7 segment (red, green), control output bar graph (red, green), LED typ			
leating, Cooling				
leating & Cooling	ON/OFF, P, PI, PD, PID Control			
	Thermocouple, RTD: 1 to 100 (0.1 to 100.0) °C/°F Analog: 1 to 100 digit			
nal band (P)	0.1 to 999.9 °C/°F (0.1 to 999.9%)			
ne (I)	0 to 9,999 sec			
time (D)	0 to 9,999 sec			
cle (T)	•0.1 to 120.0 sec [relay output model] •1.0 to 120.0 sec [SSR drive output model]			
set	0.0 to 100.0%			
1echanical	≥ 10,000,000 operations			
lectrical	\geq 100,000 operations (load resistance: 250 VAC \sim 3 A)			
strength	Between the charging part and the case: 3,000 VAC \sim 50/60 Hz for minute			
	0.75 mm amplitude at frequency of 5 to 55 Hz in each X, Y, Z direction for 2 hours			
resistance	\geq 100 M Ω (500 VDC== megger)			
unity	± 2 kV square shaped noise (pulse width 1 μs) by noise simulator R-phase, S-phase			
tention	pprox 10 years (non-volatile semiconductor memory type)			
emperature	-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)			
umidity	35 to 85%RH, storage: 35 to 85%RH (no freezing or condensation)			
structure	IP65 (front panel, IEC standards)			
	Double or reinforced insulation (mark: ,, dielectric strength betwee the measuring input part and the power part: 2 kV)			
type	CE紧图			
type on ⁰¹⁾	• KPN52□-□: ≈ 160 g (≈ 230 g) • KPN53□-□: ≈ 160 g (≈ 230 g) • KPN55□-□: ≈ 220 g (≈ 316 g)			
ur	nidity ructure pe			

01) Certification attainment may vary depending on the model. Check the certification on the Autonics website.

Communication Interface

RS485	
Comm. protocol	Modbus RTU
Connection type	RS485
Application standard	EIA RS485 compliance with
Maximum connection	31 units (address: 01 to 127)
Synchronous method	Asynchronous
Comm. Method	Two-wire half duplex
Comm. effective range	\leq 800 m
Comm. speed	2,400 / 4,800 / 9,600 (default) / 19,200 / 38,400 bps (parameter)
Response time	5 to 99 ms (default: 20 ms)
Start bit	1 bit (fixed)
Data bit	8 bit (fixed)
Parity bit	None (default), Odd, Even
Stop bit	1 bit, 2 bit (default)
EEPROM life cycle	pprox 1,000,000 operations (Erase / Write)

Input Type and Using Range

The setting range of some parameters is limited when using the dec	

Input typ	Input type		Display	Using range (°C)	Using range (°F)
	14 (CA)	1	E C. E 1	-200 to 1,350	-328 to 2,462
	K (CA)	0.1	F C.F 5	-199.9 to 999.9	-199.9 to 999.9
	J (IC)	1	Е [. J	-200 to 800	-328 to 1,472
	J (IC)	0.1	F C.7 5	-199.9 to 800.0	-199.9 to 999.9
	E (CR)	1	EC.E I	-200 to 800	-328 to 1,472
		0.1	E C.E 2	-199.9 to 800.0	-199.9 to 999.9
	T (CC)	1	E [.E	-200 to 400	-328 to 752
	(CC)	0.1	£ [.£ 2	-199.9 to 400.0	-199.9 to 752.0
Thermo	B (PR)	1	ЕС-Б	0 to 1,800	32 to 3,272
-couple	R (PR)	1	£[-r	0 to 1,750	32 to 3,182
coupie	S (PR)	1	£C-5	0 to 1,750	32 to 3,182
	N (NN)	1	£[-n	-200 to 1,300	-328 to 2,372
	C (TT) 01)	1	<i>ЕС-С</i>	0 to 2,300	32 to 4,172
	G (TT) 02)	1	ЕС- Б	0 to 2,300	32 to 4,172
	L (IC)	1	EC.LI	-200 to 900	-328 to 1,652
		0.1	E C.L 2	-199.9 to 900.0	-199.9 to 999.9
	U (CC)	1	E [. U	-200 to 400	-328 to 752
		0.1	F C.U 5	-199.9 to 400.0	-199.9 to 752.0
	Platinel II	1	EC-P	0 to 1,390	32 to 2,534
	Cu50 Ω	0.1	C U.S D	-199.9 to 200.0	-199.9 to 392.0
	Cu100 Ω	0.1	C U. 1 D	-199.9 to 200.0	-199.9 to 392.0
	JPt100 Ω	1	JPE.I	-200 to 650	-328 to 1,202
RTD		0.1	JPE.2	-199.9 to 650.0	-199.9 to 999.9
KID	DPt50 Ω	0.1	d P E.S	-199.9 to 600.0	-199.9 to 999.9
	DPt100 Ω	1	dPE.1	-200 to 650	-328 to 1,202
		0.1	dPt.2	-199.9 to 650.0	-199.9 to 999.9
	Nickel120 Ω	1	n1.12	-80 to 200	-112 to 392
	0 to 10 V	-	R-u I)~ 10 V
	0 to 5 V	-	8-u2)~ 5 V
Analog	1 to 5 V	-	R-u3		~ 5 V
malog	0 to 100 mV	-	R.nu I)~ 100 mV
	0 to 20 mA	-	R.5.8 I	()~ 20 mA
	4 to 20 mA	-	8.5.8.2	4	I~ 20 mA

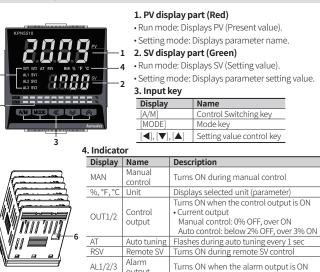
01) C (TT): Same as existing W5 (TT) type sensor

02) G (TT): Same as existing W (TT) type sensor \bullet Permissible line resistance per line: $\leq 5~\Omega$

Display accuracy

Input type	Using temperature	Display accuracy
Thermo -couple RTD	At room temperature (23°C ±5 °C)	• Thermocouple C, G and R, S below 200 °C: (PV $\pm 0.3\%$ or ± 3 °C higher one) ± 1 -digit • Thermocouple B below 400 °C: There is no accuracy standards (PV $\pm 0.5\%$ or ± 2 °C higher one) ± 1 -digit
	Out of room temperature range	• RTD Cu50 Ω, DPt50 Ω: (PV ±0.5% or ±3 °C higher one) ±1-digit • Thermocouple R, S, B, C, G: (PV ±0.5% or ±10 °C higher one) ±1-digit • Other sensors: ≤ ±5 °C (≤-100 °C)
Analog	At room temperature (23°C ±5 °C)	±0.3% F.S. ±1-digit
Analog	Out of room temperature range	±0.5% F.S. ±1-digit

Unit Descriptions



Multi SV displayed. (When using multi SV function) 5. Bar graph: Refer to 'Bar Graph'.

output

SV1/2/3

6. PC loader port: For connecting communication converter

The SV indicator is ON which is currently

(sold separately).

Bar Graph

MV of control output (OUT1, OUT2) is displayed as the bar graph in real-time. According to bar graph setting in parameter 5 group, it displays bar graph by control output or does not display it.

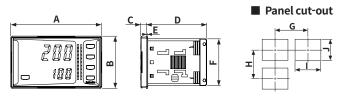


One LED is 10% (total 10 LEDs: 100%). If control output MV is 0.1 to 10%, one LED turns ON. If MV is 90.1 to 100%, 10 LEDs turn ON.

The 1 output type (heating or cooling control) model has one OUT1 bar graph (red). The 2 output type (heating & cooling control) model has two bar graphs: OUT1 bar graph (red), OUT2 bar graph (green). OUT1 is for heating MV and OUT2 is for cooling MV.

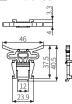
Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.

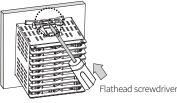


	Body						Panel cut-out			
	A	В	С	D	E	F	G	Н	I	J
KPN52	96	48	6	64.5	1.5	44.7	\geq 115	≥ 65	92+0.8	45 ^{+0.6}
KPN53	48	96	6	64.5	1.5	91.5	≥ 65	\geq 115	45 ^{+0.6}	92 ^{+0.8}
KPN55	96	96	6	64.5	1.5	91.5	\geq 115	\geq 115	92 ^{+0.8}	92 ^{+0.8}

Bracket



Installation Method



Insert the unit into a panel, fasten the bracket by pushing with tools with a flathead screwdriver.

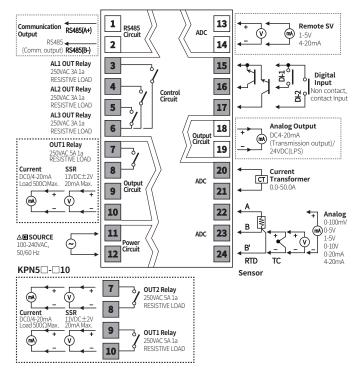
Errors

Display	Input	Description	Output	Troubleshooting	
Temperature sensor		Flashes at 0.5 sec interval when input sensor is disconnected or sensor is not connected.	'Sensor error, MV' parameter setting value	Check input sensor status.	
orcn	Analog	Flashes at 0.5 sec interval when input is over F.S. $\pm 10\%$.	'Sensor error, MV' parameter setting value	Check analog input status.	
нннн	Temperature sensor	Flashes at 0.5 sec intervals if the input value is above the input range. ⁰¹	Heating: 0%, Cooling: 100%		
пппп	Analog	Flashes at 0.5 sec intervals if the input value is over 5 to 10% of high limit or low limit value.	Normal output	When input is within the rated	
Temperature sensor		Flashes at 0.5 sec. intervals if the input value is below the input range. ⁰¹	Heating: 100%, Cooling: 0%	input range, this display disappears.	
LLLL	Analog	Flashes at 0.5 sec intervals if the input value is over 5 to 10% of low limit or high limit value.	Normal output		
Err	Temperature sensor	Flashes at 0.5 sec intervals if there is error for setting and it returns to	-	Check setting	
	Analog	the error-before screen.		method.	

01) Be careful that when HHHH / L L L L error occurs, the control output may occur by recognizing the maximum or minimum input depending on the control type.

Connections

Shaded terminals are standard model.



Crimp Terminal Specifications

• Unit: mm, Use the crimp terminal of follow shape.

≤5.8 Fork crimp terminal



Round crimp terminal

Initial Display When Power is ON

When power is supplied, after all display will flash for 1 sec, model name is displayed sequentially. After input sensor type will flash twice, enter into RUN mode.

	1. All display	2. Model	3. Input specification	4. Run mode
PV display part	8.8.8.8	EP53	EP53	oPEn
SV display part	8.8.8.8	11.23	E [. 2] I	٥

Mode Setting

	Auto before entering to mode (When using password)	\rightarrow	Password input	Pass Fail	Key input Auto [◀], [▲], [▼ [MODE]	Se 7] Pa	Itering moo lected moo Issword inp In mode	de
	$[\blacktriangleleft], [\blacktriangle], [\blacktriangledown]$	→	SV setting			ave: [MOE r no key ii ver 3 sec		\bigcap
RUN	[MODE]	\rightarrow	Parameter Group	[MODE] over 3 sec		\rightarrow		
	$[\blacktriangleleft] + [\blacktriangle] + [\blacktriangledown]$ over 5 sec	\rightarrow	Parameter reset	Refer to	o 'Paramete	r Reset'	\rightarrow	RUN
	[A/M]	→	Auto/Manual Control Switching	[A/M]			\rightarrow	
	[▲] + [▼] over 3 sec	\rightarrow	Digital input	Auto			\rightarrow	

Parameter Reset

- 01. Press the [◀] + [▲] + [▼] keys for over 5 sec. in run mode, INIT turns ON.
- 02. Change the setting value as YES by pressing the $[\blacktriangle]$, $[\nabla]$ keys.
- 03. Press the [MODE] key to reset all parameter values as default and to return to run mode.

Parameter Setting

- · Some parameters are activated/deactivated depending on the model or setting of other parameters.
- The 'Parameter mask' feature, which hide unnecessary or inactive parameters, and the 'User parameter group' feature, which quickly and easily set up certain parameters that are frequently used, can be set up in DAQMaster. • Refer to the user manual for the details.

_ _

Parameter 1 group

	sioup	
Parameter	Display	Default
Control output RUN/STOP	r - 5	rUn
Multi SV selection	50-0	5 u - O
Heater current monitoring	C E - A	0.0
Alarm output1 low limit	AL IL	1550
Alarm output1 high limit	AL I.H	1550
Alarm output2 low limit	A L 2.L	1550
Alarm output2 high limit	A L 2.H	1550
Alarm output3 low limit	A L 3.L	1550
Alarm output3 high limit	A L 3.H	1550
Multi SV 0	5u-0	0000
Multi SV 1	5u-1	0000
Multi SV 2	50-2	0000
Multi SV 3	5u-3	0000

Parameter 2 group					
Parameter	Display	Default			
Auto tuning RUN/STOP	ЯĿ	oFF			
Heating proportional band	H - P	0 10.0			
Cooling proportional band	[- P	0 10.0			
Heating integral time	H-1	0000			
Cooling integral time	E - 1	0000			
Heating derivative time	Н- d	0000			
Cooling derivative time	[-d	0000			
Dead overlap band	dь	0000			
Manual reset	rESE	0 5 0.0			
Heating hysteresis	н.н у 5	200			
Heating OFF offset	H.o S E	000			
Cooling hysteresis	C.H Y S	200			
Cooling OFF offset	C.oSt	000			
MV low limit	L-ñu	+00.0			
MV high limit	H-ñu	100.0			
RAMP up change rate	r A ñ U	000			
RAMP down change rate	r Añd	000			
RAMP time unit	r.Unt	ñ! n			

Parameter 3 group

ParameterDisplayDefaultInput specification $I \cap - E$ $UCRH$ Temperature unit $U \cap I E$ $\circ C$ Analog low limit $L - r G$ $D D D D$ Analog low limit $H - r G$ $D D D D$ Analog high limit $H - r G$ $D D D D$ Scaling decimal point $d \circ E$ $D D D$ Low limit scale $L - SC$ $D D D D$ Display unit $d U n E$ $\circ r o$ Input correction $I n - b$ $D D D D$ Input digital filter $\overline{n}R u F$ $D D D D$ SV low limit $L - S u$ $-2 D D$ SV low limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Vow limit $L - S u$ $-2 D D$ Outrol output mode $R E E$ $E U n I$ Number: 1) $S S r$ $(Output number: 2)$ OUT1 control output $a U E P$ $S S r$ OUT2 control output $a U E P$ $S S r$ OUT2 current output $a U E P$ $S S r$ OUT2 current output $a U E P$ $S S r$ OUT2 current output $a U E $								
Temperature unit Unit \circ [Analog low limit $L - r \subseteq$ DDDD Analog high limit $H - r \subseteq$ DDDD Scaling decimal point dat DD Low limit scale $L - S \subseteq$ DDDD High limit scale $H - S \subseteq$ DDDD Display unit $dUnt$ \circ ro Input digital filter $\vec{n} R \cup F$ DDDD SV low limit $L - S \cup$ - 20D SV low limit $L - S \cup$ - 20D SV high limit $H - S \cup$ - 20D SV hold limit $H - S \cup$ - 20D SV hold limit $H - S \cup$ - 20D SV hold limit $H - S \cup$ - 20D SV hold limit $H - S \cup$ - 20D SV hold limit $H - S \cup$ - 20D SV hold limit $H - S \cup$ - 20D Sv hold limit $H - S \cup$ - 20D Sv hold limit $H - S \cup$ - 20D Volt correction output mode $a - F t =$ (Output number: 2) OUT1 control output $a Ut t =$ - 7 t =	Parameter	Display	Default					
Analog low limitL $-r G$ D D DAnalog low limitH $-r G$ D D DAnalog high limitH $-r G$ I D DScaling decimal pointd $o E$ D DLow limit scaleL $-SC$ D D DHigh limit scaleH $-SC$ I D DDisplay unitd U h E $-r G$ Input correctionI $n - b$ D D DInput digital filter $\overline{n}R uF$ D D DSV low limitL $-S u$ $-2 D D$ SV low limitH $-S u$ I 3 S DVow limit $H - S u$ I 3 S DVow limit $-F E$ (Output number: 1)Not the selection $-F E$ (Output number: 2)OUT1 current output range $a U E E$ S S rOUT2 current output range $a U E E$ S S rOUT2 current output range $a 2 \overline{-} R$ $4 - 2 D$ Heating control cycle $H - E$ $2 C D (Relay)$ Concling control cycle $H - E$ $2 C D (Relay)$ Concling control cycle $H - E$ $2 C D R (Relay)$	Input specification	In-E						
Analog high limit $H - r G$ I IIIII Scaling decimal point $d \circ E$ IIIII Low limit scale $L - SC$ IIIIII High limit scale $H - SC$ IIIIIII Display unit $d U I E$ $9 - r \circ$ Input correction $I n - b$ IIIIII Input digital filter $\bar{n} R \omega F$ IIIIII SV low limit $L - S \omega$ -200 SV low limit $L - S \omega$ -200 SV low limit $H - S \omega$ 1350 SV low limit $H - S \omega$ 1350 Control output mode $o - F E$ $H E R \omega$ Control output mode $o - F E$ $H C R \omega$ Auto tuning mode $R E E$ $E U n 1$ Auto tuning mode $R E E$ $E U n 1$ $OUT1 control output selection o U E I number: 1 OUT1 current output range o L \bar{n} R 4 - 20 OUT2 control output range o U E Z S S r OUT2 current output range a 2 \bar{n} R 4 - 20 Heating control cycle H - E 2C 20 <$	Temperature unit	Unit	٥٢					
Scaling decimal point $d \circ t$ Ωg Low limit scale $L - 5 [$ $\Omega g \Omega g$ High limit scale $H - 5 [$ $I \Omega g \Omega g$ Display unit $d U \wedge t$ $\circ \prime \circ o$ Input correction $I \cap - b$ $\Omega g \Omega g$ Input digital filter $\vec{n} R \cup F$ $\Omega g \Omega g$ SV low limit $L - 5 \cup$ $- 2 \Omega g$ SV low limit $H - 5 \cup$ $I 3 S G$ Control output mode $o - F E$ $H E R L$ (Output number: 1)Control output mode $o - F E$ $H E R L$ (Output number: 2)Auto tuning mode $R L E$ $E U \cap I$ (Output number: 2)OUT1 control output selection $o U E I$ $r L S I$ (Output number: 2)OUT1 current output range $o U E Z$ $S S r$ (Output number: 2)OUT2 control output range $o U E Z$ $S S r$ (Output number: 2)Heating control cycle $H - E$ $H - E$ $2 C Q G$ (Relay)Concling control cycle $H - E$ $U D Q D Q$	Analog low limit	L-rG	0 0.0 0					
Low limit scaleL - 5[D 0.0High limit scale $H - 5[$ 100.0Display unit $dUnt$ $o'ro$ Input correction $I n - b$ D 0.0Input correction $I n - b$ D 0.0Input digital filter $\bar{n}R\omega F$ D 0.0SV low limit $L - 5u$ - 200SV low limit $H - 5u$ 1350Control output mode $o - F E$ $HERE_{(Output number: 1)}$ Control output mode $o - F E$ $PI d$ Control type $E - \bar{n}d$ $PI d$ OUT1 control output selection $oUE I$ $number: 1)$ OUT1 control output range $o L\bar{n}R$ $H - 20$ OUT1 current output range $o L\bar{n}R$ $H - 20$ OUT2 control output range $oUE Z$ $S5r$ OUT2 current output range $oUE Z$ $S5r$ OUT2 control output range $oZ\bar{n}R$ $H - 20$ Heating control cycle $H - E$ $U20d$ Golding control cycle $H - E$ $U2dD$ Realing control cycle $H - E$ $U2dD$ Concling control cycle $H - E$ $U2dD$ Realing control cycle $H - E$ $U2dD$ Concling control cycle $H - E$ U	Analog high limit	Н-гБ	10.00					
High limit scale $H - 5C$ $I 0 0 0$ Display unit $dU h E$ $o \neq o$ Input correction $I h - b$ $0 0 0 0$ Input digital filter $\bar{n} R u F$ $0 0 0 1$ SV low limit $L - 5 u$ $- 200$ SV high limit $H - 5 u$ 1350 Control output mode $o - F E$ $HERE$ (Output number: 1)Control type $E - \bar{n} d$ $PI d$ (Output number: 2)Auto tuning mode REE $E Uh r I$ (Output number: 2)OUT1 control output selection $o UE I$ $r L Y$ (Output number: 2)OUT1 current output range $o UE Z$ $55r$ (Output number: 2)OUT2 control output range $o UE Z$ $55r$ (Output rangeOUT2 control output range $o UE Z$ $55r$ (Output rangeHeating control cycle $H - E$ $U CallU D DU Call Q Call(Relay)$	Scaling decimal point	dot	0.0					
Display unit $dUnt$ $0'ra$ Input correction $1 n - b$ $DDDD$ Input digital filter $\bar{n}R uF$ $DDDI$ SV low limit $L - 5u$ $-2DD$ SV low limit $H - 5u$ $135D$ Control output mode $a - FE$ $HERE$ (Output number:1)Control output mode $a - FE$ $HERE$ (Output number:2)Auto tuning mode REE $E Unit(Outputnumber:2)Auto tuning modeREEE Unit(Outputnumber:2)OUT1 control outputselectiona UE Ir L Y(Outputnumber:2)OUT1 current outputrangea UE IS5r(OutputrangeOUT2 control outputrangea UE ZS5r(OutputrangeOUT2 current outputrangea 2.\bar{n}R4 - 20(Relay)Heating control cycleH - ED2DD(Relay)$	Low limit scale	L - 5 C	0 0 0.0					
Input correction I $n - b$ I I I I I I I I I I I I I I I I I I I	High limit scale	H - 5 C	100.0					
Input digital filter $\vec{n}R_{\omega}F$ $\Omega \square \Omega_{-1}$ SV low limit $L - 5 \omega$ $- 2 \square \Omega_{-1}$ SV low limit $H - 5 \omega$ $- 2 \square \Omega_{-1}$ SV low limit $H - 5 \omega$ $- 2 \square \Omega_{-1}$ SV high limit $H - 5 \omega$ $- 2 \square \Omega_{-1}$ Control output mode $o - F E$ $HERE_{-1}$ Control output mode $o - F E$ $HERE_{-1}$ Control type $E - \bar{n} d$ $PI d$ Output mode REE $E U n I$ Auto tuning mode REE $E U n I$ OUT1 control output selection $o UE I$ $number: 1$) OUT1 current output range $o L \bar{n}R$ $4 - 2\Omega$ OUT2 control output range $o L \bar{n}R$ $4 - 2\Omega$ OUT2 current output range $a 2 \bar{n}R$ $4 - 2\Omega$ Heating control cycle $H - E$ $2 C \Omega D$ Heating control cycle $H - E$ $2 C \Omega D$	Display unit	d.U n E	ہ ہے					
SV low limit $L - 5u$ -200 SV high limit $H - 5u$ 1350 SV high limit $H - 5u$ 1350 Control output mode $a - FE$ $HERE_{(Output number: 1)}$ $number: 1$ $H - C$ $(Output number: 2)$ $HERE_{(Output number: 2)}$ Control type $E - \bar{n}d$ $PI d$ $(Output number: 2)$ $PI d$ Auto tuning mode REE $EUn I$ $0UT1$ control output selection $aUE I$ $r L Y$ $OUT1$ control output range $a L \bar{n}R$ $H - 20$ $OUT2$ control output range $a UE Z$ $55r$ $OUT2$ current output range $a 2 \bar{n}R$ $H - 20$ $OUT2$ current output range $a 2 \bar{n}R$ $H - 20$ Heating control cycle $H - E$ $22aB$ (Relay) $0DDD$ $0DDD$	Input correction	In-b	0000					
SV high limit $H - 5 u$ 1350 Control output mode $a - FE$ $HERE_{(Output number: 1)}$ Control output mode $a - FE$ $HERE_{(Output number: 2)}$ Control type $E - \bar{n}d$ $PI d$ Control type $E - \bar{n}d$ $PI d$ Output number: 2) $number: 2)$ $number: 2)$ Auto tuning mode REE $EUn I$ OUT1 control output selection $aUE I$ $(Output number: 2)$ OUT1 current output range $a L \bar{n}R$ $4 - 20$ OUT2 control output range $a UE \bar{c}$ $55r$ OUT2 current output range $a 2 \bar{c} \bar{n}R$ $4 - 20$ Heating control cycle $H - E$ $Q2dB$ (Relay) $Q0DD$ $Q0DD$			000.1					
Control output mode $a - F E$ $HERE_{(output number: 1)}(umber: 1)$ Control output mode $a - F E$ $[(output number: 2)](umber: 2)$ Control type $E - \bar{n}d$ $PI d$ Auto tuning mode REE $E Un 1$ Auto tuning mode REE $E Un 1$ OUT1 control output selection $a UE I$ $number: 2)$ OUT1 current output range $a L\bar{n}R$ $4 - 20$ OUT2 control output range $a UE Z$ $55r$ OUT2 current output range $a UE Z$ $55r$ OUT2 current output range $a 2.\bar{n}R$ $4 - 20$ Heating control cycle $H - E$ $DZLD$ Goaling control cycle $H - E$ $DZLD$		L-Su						
Control output mode $o - F E$	SV high limit	H-Su						
Control output mode $a - F E$ number: 1) (Output number: 2) Control type $E - \bar{n}d$ $PI d$ (Output number: 1) Control type $E - \bar{n}d$ $PI d$ (Output number: 1) Auto tuning mode REE $E Un I$ OUT1 control output selection $aUE I$ $OUput$ number: 2) OUT1 control output range $a L\bar{n}R$ $4 - 2D$ OUT2 control output range $a UE Z$ $S5r$ OUT2 control output range $a UE Z$ $S5r$ OUT2 current output range $a 2\bar{n}R$ $4 - 2D$ Heating control cycle $H - E$ $UEaD$ (Relay)								
Control output mode $a - F E$ $H - E$ (output number: 2) $number: 2)$ Control type $E - \overline{n} d$ $[output number: 2)$ Auto tuning mode $R E E$ $E Un i$ Auto tuning mode $R E E$ $E Un i$ OUT1 control output selection $a UE I$ $number: 2)$ OUT1 current output range $a U E I$ $number: 2)$ OUT2 control output range $a U E Z$ $55r$ OUT2 control output range $a U E Z$ $55r$ OUT2 current output range $a 2.\overline{n} R$ $4 - 20$ Heating control cycle $H - E$ $U E Z$ Concling control cycle $H - E$ $U E Q D$ Gouling control cycle $H - E$ $U Q D D$			(Output					
$\begin{array}{c c} & (Output \\ number: 2) \\ Pi & I \\ \hline Pi & Pi \\ \hline Pi \\ Output \\ number: 1) \\ \hline Pi \\ Output \\ number: 2) \\ \hline Pi \\ Output \\ number: 2) \\ \hline Output \\ number: 2) \\ \hline Output \\ output \\ selection \\ \hline OUT1 control output \\ selection \\ OUT1 current output \\ range \\ OUT1 current output \\ range \\ OUT1 current output \\ range \\ OUT2 control output \\ selection \\ OUT2 current output \\ range \\ Heating control cycle \\ H - t \\ OUT2 current output \\ range \\ \hline Output \\ P \\ Output \\ $	Control output mode	0 - F Ł						
Control type $\begin{bmatrix} P \mid d \\ (output \\ number: 1) \\ P,P \\ (output \\ number: 2) \\ Reverse end end end end end end end end end en$								
Control type $\mathcal{L} - \bar{n}d$ $\begin{array}{c} (Output \\ number: 1) \\ \mathcal{P} \\ (Output \\ number: 2) \\ (Output \\ number: 2) \\ \mathcal{P} \\ \mathcal{P} \\ (Output \\ number: 2) \\ \mathcal{P} \\$								
Control type $E - \bar{n} d$ number: 1) P_{P} Auto tuning mode RLL $E U n I$ $number: 2)$ Auto tuning mode RLL $E U n I$ $number: 2)$ OUT1 control output selection $oUE I$ $number: 2)$ $OUtput number: 2)$ OUT1 current output range $o L\bar{n}R$ $4 - 2D$ $OUT2$ control output selection $oUE Z$ $55r$ OUT2 control output range $o 2\bar{n}R$ $4 - 2D$ $OUT2$ current output range $a2\bar{n}R$ $4 - 2D$ Heating control cycle $H - E$ $D2DD$ $(Relay)$ Cooling control output $D DD$ $D DD$ $D DD$								
Control type L - nd P,P (Output number: 2) Auto tuning mode REL E Un 1 Auto tuning mode REL E Un 1 r L 9 OUT1 control output selection a UE 1 Inumber: 2) OUT1 current output range a UE 2 S5r OUT2 control output range a UE 2 S5r OUT2 control output range a UE 2 S5r OUT2 current output range a 2.5.7 4 - 2.0 Heating control cycle H - E D20.0 (Relay) Cooling control cycle F - L D0.02								
number: 2) Auto tuning mode $R L L$ $U L r I$ OUT1 control output selection $a U L I$ $r L Y$ OUT1 control output range $a U L I$ $r L Y$ OUT1 current output range $a U L I$ $r U Y$ OUT2 control output range $a U L Z$ $5 S r$ OUT2 control output range $a U L Z$ $5 S r$ OUT2 current output range $a 2 L R$ $4 - 2 D$ Heating control cycle $H - L$ $2 C a D$ (Relay) Cooling control output $S L L$ $D D D D$	Control type	L-nd						
Auto tuning mode REL E Un I OUT1 control output selection oUE I r.L y (Output number: 1) OUT1 current output range o L \vec{n} R 4 - 20 OUT2 control output range o UE 2 55 r OUT2 control output range o UE 2 55 r OUT2 current output range o 2.\vec{n} R 4 - 20 Heating control cycle H - E 020.0 (Relay)								
OUT1 control output selection $a U \vdash I$ $r \lfloor Y \\ (outputnumber: 1) OUT1 control outputrange a U \vdash R r \downarrow S r OUT1 current outputrange a \downarrow \bar{r} R 4 - 20 OUT2 control outputrange a \downarrow \bar{r} R 4 - 20 OUT2 current outputrange a \downarrow \bar{r} R 4 - 20 OUT2 current outputrange a 2 \bar{r} R 4 - 20 Heating control cycle H - L D200(Relay) Cooling control cycle F - L D000 $								
OUT1 control output selection $oUEI$ $(Outputnumber: 1)$ OUT1 control output range $oUEI$ $155r$ OUT1 current output range $oUE2$ $55r$ OUT2 control output selection $oUE2$ $55r$ OUT2 current output range $oUE2$ $55r$ OUT2 current output range $o2.7R$ $4-20$ Heating control cycle $H-E$ $22dB$ (Relay) Cooling control output $00L2$ $00D2$	Auto tuning mode	HE.E						
OUT1 control output selection oUE I number: 1) 55 r (Output number: 2) OUT1 current output range o LRR 4 - 20 OUT2 control output selection oUE 2 55 r OUT2 current output range o2.RR 4 - 20 Heating control cycle H - E 020.0 (Relay)								
Selection S5-r (Output number:2) OUT1 current output range o LñR VIT2 control output selection oUE2 OUT2 current output range o2.ñR Heating control cycle H - E Cooling control cycle F - L	OUT1 control output							
number: 2) OUT1 current output range o Lñ R 4 - 2 D OUT2 control output selection o UE 2 5 5 r OUT2 current output range o 2.ñ R 4 - 2 D Heating control cycle H - E D 2 D D (Relay) Cooling control cycle F - L D D D D	selection	0021	55r					
OUT1 current output range a Lā R 4 - 20 OUT2 control output selection a UE 2 55 r OUT2 current output range a 2.ā R 4 - 20 Heating control cycle H - E 0200 (Relay) Cooling control cycle F - L 0000								
range a LnH 4-20 OUT2 control output selection a UE 2 55 r OUT2 current output range a 2.7 R 4 - 20 Heating control cycle H - E (Relay) 0 0000 Cooling control cycle F - L 0 0000	OUT1 ourrent output		number: 2)					
selection aUE2 55r OUT2 current output range a2.ñR 4-20 Heating control cycle H-E 020.0 (Relay)	range	o 1.5A	4-20					
OUT2 current output range $\sigma 2.\overline{n} R$ $4 - 20$ Heating control cycle $H - E$ $D 20.0$ (Relay) Cooling control cycle $F - E$ $D 0.00$		oUE2	55-					
range DE.N.R. Heating control cycle H - E Cooling control cycle Cooling control cycle								
Heating control cycle H - E 0200 (Relay)		o 2.ñ A	4-20					
Capiling control cyclo		Н-Е						
	Cooling control cycle	C - E						

Parameter 4 group										
Parameter	Display	Default								
Alarm output1 operation	AL-I	JUE								
mode		AL-A								
Alarm output1 option Alarm output1	AL LE									
Hysteresis	8 LH 9	001								
Alarm output1 contact type	A Lo	no								
Alarm output1 ON delay	A Lon	0000								
time Alarm output1 OFF delay	A 1.o F	0000								
time Alarm output2 operation	AL-2]]du								
Mode		AL-A								
Alarm output2 option Alarm output2 hysteresis	A F 5'F 8 5'H 7	001								
Alarm output2 rigiteresis										
type	A 5.0	no								
Alarm output2 ON delay time	A 2.o n	0000								
Alarm output2 OFF delay time	A 2.o F	0000								
Alarm output3 operation mode	AL-3	ιья								
Alarm output3 option	A L 3.E	AL-A								
Alarm output3 hysteresis	R 3.H Y	001								
Alarm output3 contact type	R 3.n	no								
Alarm output3 ON delay time	R 3.o n	0000								
Alarm output3 OFF delay time	A 3.o F	0000								
LBA time	LЬЯ.Е	0000								
LBA band	L 6 A.6	500								
Analog transmission output	R o.ñ	Pu								
PV transmission output low limit	F 5 - L	- 200								
PV transmission output high limit	F 5 - H	1350								
Communication address	Adr 5	01								
Communication speed	6Р5	96								
Comm. parity bit	Prty	nonE								
Comm. stop bit	SEP	5								
Response time	r 5 ½ E	20								
Comm. write	[oñŸ	E n.A								
Parameter 5 g										
Parameter	Display	Default								
Multi SV number Digital input key	n E.Su d I - E	1 520P								
Digital input 1 Terminal	di - i	oFF								
Function Digital input2 Terminal										
Function	d1 - 5	oFF								
Remote SV	r E.S u	oFF								
Remote SV low limit correction	r In.b	٥								
Remote SV high limit gradient correction	r 5 P n	1.0 0								
Bar graph	ЬЯг	OUE I (Output number: 1)								
Manual control, initial		(Output number: 1)								
MV	l E.ñu	AUto								
Manual control, preset MV	Pr.ñu	000.0								
Sensor error, MV	Er.ñu	000.0								
Control stop, MV Control stop, alarm	St.ñu	000.0								
output	SE.AL	Cont								
User level	USEr	Stod								

USEr

L C.5 u

L C.P I

L C.P 2

L С.Р Э

L С.Р Ч

L C.P 5

User level

SV setting lock

Parameter 1 group lock

Parameter 2 group lock

Parameter 3 group lock

Parameter 4 group lock

Parameter 5 group lock

Password setting

Stnd

oFF

oFF

οFF

oFF

oFF

oFF

PY4 0000

Function: Alarm

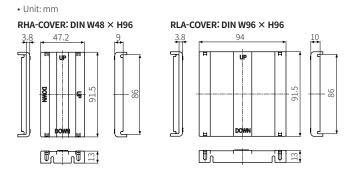
888.8 Alarm Alarm operation option

Set both alarm operation and alarm option by combining. Each alarm operates individually in two alarm output models. When the current temperature is out of alarm range, alarm clears automatically.

Opera			H: Alarm output hysteresis			
Name	Alarm operation	Description				
-	-		No alarm output			
Deviation high limit	OFF HON SV PV 100°C 110°C	OFF H ON PV SV 90°C 100°C	If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm			
	High deviation: Set as 10°C	High deviation: Set as -10°C	output will be ON.			
	ON H OFF	ON H OFF	If deviation between PV			
Deviation low limit	A PV SV 90°C 100°C	SV PV 100°C 110°C	and SV as low limit is higher than set value of deviation temperature, the alarm			
	Low deviation: Set as 10°C	Low deviation: Set as -10°C	output will be ON.			
Deviation high, low limit	ON H O PV S 90°C 100	If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the				
	High, Low devia	alarm output will be ON.				
Deviation high, low limit reverse	OFF H O A PV S 90°C 100	If deviation between PV and SV as high/low-limit is lower than set value of deviation temperature, the alarm				
	High, Low devia	output will be OFF.				
Absolute value high limit	OFF H ON PV SV 90°C 100°C	OFF H ON SV PV 100°C 110°C	If PV is higher than the absolute value, the output will be ON.			
	Absolute value: Set as 90°C	Absolute value: Set as 110°C				
Absolute value low limit	ON H OFF PV SV 90°C 100°C Absolute value: Set as 90°C	ON H OFF SV PV 100°C 110°C Absolute value: Set as 110°C	If PV is lower than the absolute value, the output will be ON.			
		Absolute value: Set as 110 C	It will be ON when it detects			
Sensor break	-		sensor disconnection.			
Heater break	-		It will be ON when it detects heater disconnection.			
Loop break	-		It will be ON when it detects loop disconnection.			
Option	n					

Name	Description	Condition of re-apply								
Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.	-								
Alarm latch	If it is an alarm condition, alarm output is ON and maintains ON status.	-								
Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.	Davida								
Alarm latch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second Lalarm condition, alarm latch operates.	Power ON								
Standby sequence 2	First alarm condition is ignored and from second alarm condition, standard alarm operates. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.	Power ON, change SV, change alarm								
Alarm latch and standby sequence 2	Basic operation is same as alarm latch and standby sequence1. It operates not only by power ON/OFF, but also alarm set value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, alarm latch operates.	temperature / operation or change STOP to RUN mode								

Sold Separately: Terminal Protection Cover



Sold Separately: Current Transformer (CT)

• Unit: mm

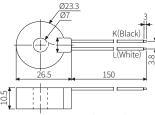
• The current for above CTs is 50A same but inner hole sizes are different. Please use this for your environment.

10

OUTPUT IN VOLTS RMS(V)

Do not supply primary current in case that CT output is open. High voltage will be generated in CT output.

CSTC-E80LN

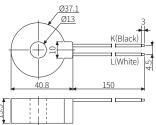




• Current ratio: 1/1000

- Wire wounded resistance: $31\Omega \pm 10\%$

CSTC-E200LN

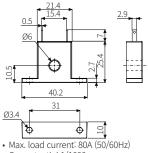




Max. load current: 200A (50/60Hz)

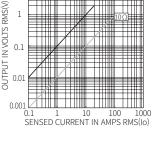
Current ratio: 1/1000
Wire wounded resistance: 20Ω±10%

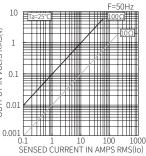
CSTS-E80PP

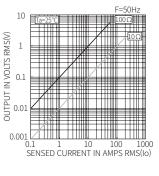


Current ratio: 1/1000

- Wire wounded resistance $31\Omega\pm10\%$







Segment Table

The segments displayed on the product indicate the following meanings. It may differ depending on the product.

7 Segment 11 Segment				10											
7 Segment			ш	Seg	mer	IT	12 Segment				16 Segment				
0	0	1	1	0	0	1	1	0	0	1	1	0	0	I	1
1	1	J	J	1	1	J	J	1	1	J	J	1	1	ŭ	J
2	2	ĥ	К	2	2	ĸ	К	2	2	К	К	2	2	ĸ	К
Э	3	L	L	З	3	L	L	Э	3	L	L	Э	3	L	L
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5	5	n	Ν	5	5	N	N	5	5	N	Ν	5	5	N	Ν
6	6	٥	0	6	6	ο	0	Б	6	ο	0	6	6	۵	0
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9	9	r	R	9	9	R	R	9	9	R	R	9	9	Ŗ	R
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d	D	U	V	d	D	V	V	d	D	Ľ	V	J	D	¥.	V
Ε	E	U.	W	Ε	Е	М	W	Ε	Е	Ы	W	Ε	E	И	W
F	F	5	Х	F	F	×	Х	F	F	×	Х	F	F	×	Х
G	G	У	Y	G	G	Ч	Y	5	G	Ч	Y	6	G	Y	Y
н	Н	Ξ	Z	н	Н	Z	Z	Н	Н	Z	Ζ	н	Н	2	Ζ